




Freeform Search

Database:	US Pre-Grant Publication Full-Text Database
	US Patents Full-Text Database
	US OCR Full-Text Database
	EPO Abstracts Database
	JPO Abstracts Database
	Derwent World Patents Index
	IBM Technical Disclosure Bulletins

Term:	L56 and (camera\$ same noise\$)	  
--------------	---------------------------------	---

Display:	<input type="text" value="10"/>	Documents in Display Format:	<input type="text" value="FULL"/>	Starting with Number	<input type="text" value="1"/>
-----------------	---------------------------------	-------------------------------------	-----------------------------------	-----------------------------	--------------------------------

Generate: ☐ Hit List ☒ Hit Count ☐ Side by Side ☐ Image

Search

Clear

Interrupt

Search History

DATE: Wednesday, January 26, 2005 [Printable Copy](#) [Create Case](#)

Set Name Query

side by side

Hit Count Set Name

result set

DB=USPT; PLUR=YES; OP=OR

<u>L58</u>	L57 and (camera\$ near5 noise\$)	5	<u>L58</u>
<u>L57</u>	L56 and (camera\$ same noise\$)	63	<u>L57</u>
<u>L56</u>	L55 and noise\$	417	<u>L56</u>
<u>L55</u>	L54 and camera\$	1382	<u>L55</u>
<u>L54</u>	global near1 positioning near1 system\$	9285	<u>L54</u>
<u>L53</u>	L52 and noise\$	0	<u>L53</u>
<u>L52</u>	L51 and GPS	1	<u>L52</u>
<u>L51</u>	5596494.pn.	1	<u>L51</u>
<u>L50</u>	L49 and noise\$	0	<u>L50</u>
<u>L49</u>	L48 and GPS\$	1	<u>L49</u>
<u>L48</u>	5506644.pn.	1	<u>L48</u>
<u>L47</u>	L45 and noise\$	1	<u>L47</u>
<u>L46</u>	L45 and (measurement near1 data)	0	<u>L46</u>
<u>L45</u>	l32 and camera\$	1	<u>L45</u>
<u>L44</u>	L42 and noise\$	0	<u>L44</u>
<u>L43</u>	L42 and (measurement near1 data)	0	<u>L43</u>

<u>L42</u>	L30 and camera\$	1	<u>L42</u>
<u>L41</u>	L40 and GPS\$	1	<u>L41</u>
<u>L40</u>	5596494.pn.	1	<u>L40</u>
<u>L39</u>	L38 and GPS\$	1	<u>L39</u>
<u>L38</u>	5506644.pn.	1	<u>L38</u>
<u>L37</u>	L36 and GPS\$	0	<u>L37</u>
<u>L36</u>	5493409.pn.	1	<u>L36</u>
<u>L35</u>	L34 and GPS\$	0	<u>L35</u>
<u>L34</u>	5410225.pn.	1	<u>L34</u>
<u>L33</u>	L32	1	<u>L33</u>
<u>L32</u>	L31 and GPS\$	1	<u>L32</u>
<u>L31</u>	5335072.pn.	1	<u>L31</u>
<u>L30</u>	L29 and GPS\$	1	<u>L30</u>
<u>L29</u>	5267042.pn.	1	<u>L29</u>
<u>L28</u>	L27 and GPS\$	0	<u>L28</u>
<u>L27</u>	4937676.pn.	1	<u>L27</u>
<u>L26</u>	L25	0	<u>L26</u>
<u>L25</u>	L24 and GPS\$	0	<u>L25</u>
<u>L24</u>	4908646.pn.	1	<u>L24</u>
<u>L23</u>	L22 and GPS\$	0	<u>L23</u>
<u>L22</u>	4774564.pn.	1	<u>L22</u>
<u>L21</u>	L20 and GPS\$	0	<u>L21</u>
<u>L20</u>	4480278.pn.	1	<u>L20</u>
<u>L19</u>	L18 and GPS\$	0	<u>L19</u>
<u>L18</u>	3772649.pn.	1	<u>L18</u>
<u>L17</u>	L16 and control\$	4	<u>L17</u>
<u>L16</u>	L15 and (measurement near1 data near1 receiv\$)	5	<u>L16</u>
<u>L15</u>	L14 and generat\$	30	<u>L15</u>
<u>L14</u>	L13 and noise\$	34	<u>L14</u>
<u>L13</u>	L10 and (measurement near1 data)	58	<u>L13</u>
<u>L12</u>	L10 and ((mearement) near1 (data or information))	0	<u>L12</u>
<u>L11</u>	L10 and (mearement near1 data)	0	<u>L11</u>
<u>L10</u>	L9 and receiv\$	807	<u>L10</u>
<u>L9</u>	L8 and record\$	845	<u>L9</u>
<u>L8</u>	L7 and GPS\$	1214	<u>L8</u>
<u>L7</u>	L6 and (global near1 positioning near1 system\$)	1382	<u>L7</u>
<u>L6</u>	camera\$	135665	<u>L6</u>
<u>L5</u>	L4 and noise\$	1	<u>L5</u>
<u>L4</u>	L3 and (measurement near1 data)	1	<u>L4</u>
<u>L3</u>	L2 and GPS	10	<u>L3</u>
<u>L2</u>	L1 and camera\$	653	<u>L2</u>

L1 Miyake, /?in

7418 L1

END OF SEARCH HISTORY